

# CHΛdeMO

# CHAdeMO TW activities and 2.0

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#### CHAdeMO TWG Activities in 2018-19 : Overview

2018								2019	)		
Jan Feb Mar Apr May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Jan	Feb	Mar	
Specification WG	* CHAdeMO 2.0 released * CHAdeMO General Assembly					CHAdel 1 draft	VIO release	* CHAdeMO 2.1 release			
Specification we		1			n Lucern e TWG	•	H				
	* CHAdeMO Europe TWG #2?										
Active SWGs :											
<ul> <li>High power</li> <li>(new HPC coupler)</li> </ul>		* Kic	ck-off M		* Technical exchange with PRC delegates #1			* Technical exchange with PRC delegates #2			
External charging	<b></b>	(De	elay)	>	* Ext-CH	G Guide	line 1.0				
• V2H				:	* V2H Gı	uideline	2.1.1 (JF	<b>)</b>		* V2H Guideline 2.1.1 (EN)	

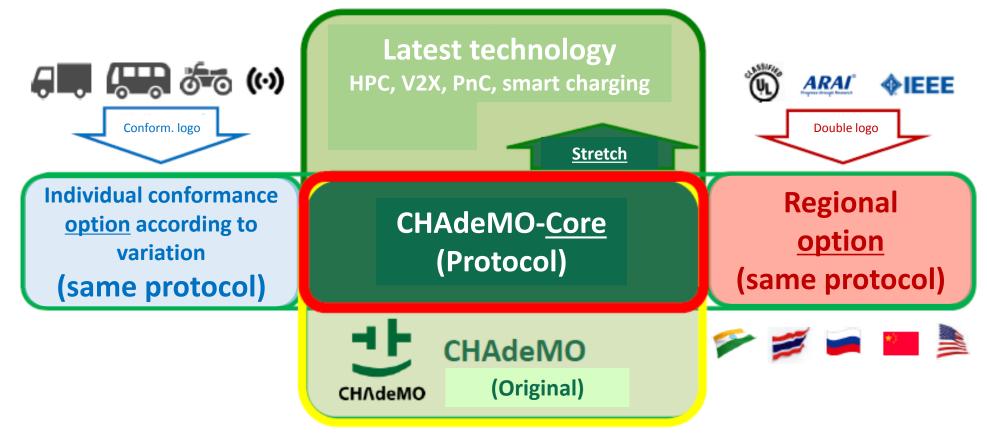


✓ No breakdowns of chargers or vehicles.
 ✓ No major issues were observed (some small software fixes).
 ✓ New 1.2/2.0 protocols were checked.
 ✓ Max. power/current was >100 kW/270 A using 'boost-mode'.



## 'CHAdeMO-Core' Technology (1)

- Requirements related to safety and interoperability -> 'Core'
- Promotion of innovation and the latest technology -> '<u>Stretch</u>' (Extended Specification)
- Respecting region-specific needs with flexibility and expandability -> 'Options'



Source: http://www.chademo.com/wp2016/wp-content/japan-uploads/2018GA/CHAdeMO2018GA.pdf



## 'CHAdeMO-Core' Technology (2)

• The five 'Core' specifications :

**1.** Connection of control pilot (d1) to the power supply of EV contactors

- allows automatic shut-off by the DC EV charging station.
- **2.** Connection of control pilot (k) to the AC/DC converter of charger
  - allows automatic shut-off by the EV.
- **3. Adoption of CAN communication** 
  - for reliable communication and compatibility with other charging standards.
- 4. Redundant control signals with CAN and hardwire (CP)
  - for additional safety.

#### **5. CHAdeMO protocol and charging/discharging sequence**

- for flexibility (more variation) and improved expandability.



#### 'CHAdeMO-Core' Technology (3)

#### • Example: adoption in IEC 61851-23-1 (ACD) draft Annex AA:

CP (normative) Charging Traction (((1))) control {((†)) Batterv unit Wireless CAN Wireless CAN Wireless communication transceiver transceiver CD1 Position detection CD2 C1 Power Traction conversion (Vdc) C2 Battery unit Earth leakage current measuring device System A station **Electric vehicle** ACD Vehicle coupler

Wireless CAN

Figure AA.1a Overall schematics of System A station with reverse-current prevention diode DI, ACD and vehicle

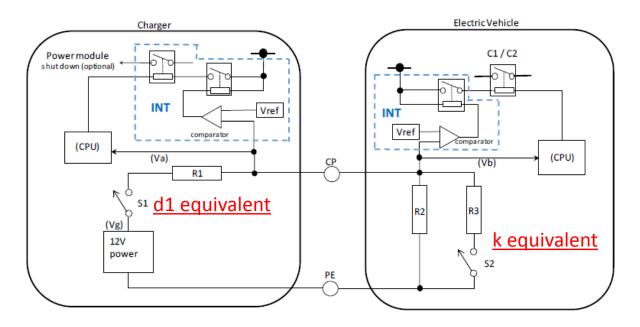


Figure AA.2a Control pilot circuit (option A) of System A station and vehicle

## CHAdeMO 2.0 Key points (1)

Туре	New/additional requirements			
.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		EVSE	EV	
Functional	The max. system voltage: 500 -> 1000V with high-voltage control.	Х	Х	
	Continuous output of 12V power supply in the proximity detection line to allow Plug & Charge (PnC).		X (opt.)	
	New CAN IDs for service code and vehicle ID option for better operability e.g. PnC.	Х	Х	
	20A/s rate limit for the 'available output current' during dynamic control.	Х	Х	
	CAN flag to update the maximum charging time during dynamic control.	Х	Х	
Functional	The upper limit of Y capacitance for systems with voltage $\leq$ 500V.	Х	Х	
& safety	The max. height (1.5m) of the holder of charging cable assembly.	Х		
Safety	Prohibition to install SPDs between the high-voltage (P and N) lines.	Х	Х	
	Overvoltage protection.	Х		
	Double or reinforced insulation between P-N, P-GND and N-GND for systems with voltage > 500V.	Х	Х	
	Sequence for allowing the welding check of the EV contactors even in case of EVSE failure (under certain conditions determined by the EVSE manufacturer).	Х	Х	
	CHAdeMO Confidential			

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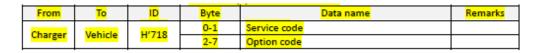
## CHAdeMO 2.0 Key points (2)

ltem	New/additional requirement	Target		
		EVSE	EV	
Others	The minimum PE conductor size (0.75mm <sup>2</sup> ).	Х	Х	
(clarification	Opto-couplers in the interface circuit can be substituted by other devices e.g.	Х	Х	
and	transistors, mechanical relays.			
improveme nt)	EV contactors should be opened within 1 sec. after PE discontinuity.		Х	
,	Transmission of the minimum battery voltage by CAN.		Х	
	Voltage measurement accuracy for systems with voltage > 500V.	Х		
	Recommended judgment criteria (10% or 20A, 1s) for current deviation error detection.		Х	



#### CHAdeMO 2.0 Plug & Charge

#### **Example of use case :**



(1) The charger detects the mating of the coupler by proximity detection. (2) The charger sends 'Service code' = XX to EV, with additional 'Option' codes (max. 6 bytes) if necessary.

(4) The IDs are authenticated and the charging session is started by turning d1 ON.

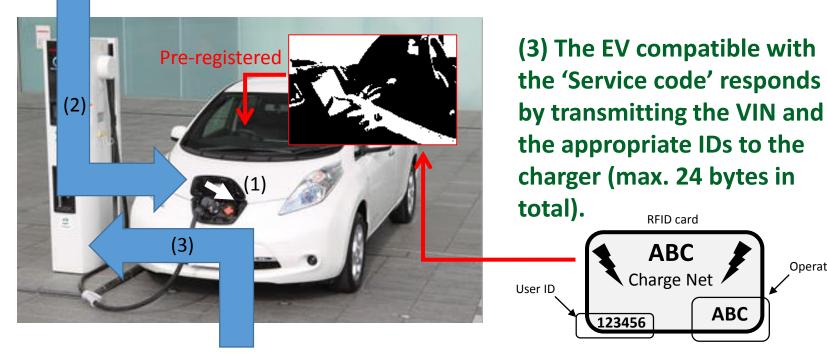
Note: XX may correspond to: 'Request to transmit VIN, charging-network operator ID and user ID.'

**RFID** card

ABC

ABC

Operator ID



From	To	ID	Byte	Data name	Remarks
		H'710	<mark>0-7</mark>	Vehicle ID	
Vehicle	Charger	H'711	<mark>0-7</mark>	Vehicle ID	
		H'712	<mark>0-7</mark>	Vehicle ID	

## High power SWG activity in FY18

#### Feasibility study of the <u>new HPC coupler</u> proposed by China

- considering the possibility of its adoption as the next-generation coupler for CHAdeMO 3.0 (TBC)... to become the new global standard / universal coupler ?



CAN communication
 Two control pilots
 Ultra-HPC ready





1500V x 600A = 900kWmax.

- other couplers may also be considered: New ? IEC 62196-3 config.FF ? ChargePoint ?
- List of SWG members: Toyota, Nissan, Honda, Mitsubishi, Subaru, Isuzu, Yazaki, Sumitomo, Hasetec, Shindengen, NS-TEXENG, Tyco Electronics, TEPCO ... plus more expected.



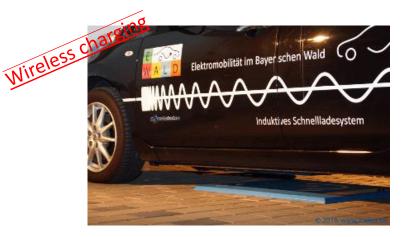
#### Ext. charging SWG: CHAdeMO Guideline 1.0

• Draft (JP) is almost ready... English version will follow shortly.





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EV/PHV/FCV Standard adoption (1) (DC-charging/V2X capable vehicles in the market)

• 22 OEM/brands, 33 vehicles... and more coming.



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EV/PHV/FCV Standard adoption (2)

\*\* JPN only

- Toyota and Honda FCVs... all equipped with CHAdeMO-V2X.
- Plug-in hybrids equipped with CHAdeMO : Mitsubishi Outlander PHEV, Toyota Prius PHV \*\*

